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Research Article

Automatic control and protection of Coal Conveyor System using PIC

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Abstract

The Coal conveyor system forms an integral part in Thermal Power plant owing to the fact that the overall efficiency of the plant is dependent on the rate at which the coal is carried to the crusher unit. But, as of now, only manual labors are employed to regularly monitor the operation of conveyor system which is highly risky. Hence, by means of a Microcontroller like PIC makes the controlling process much easier. The flaws that occur in the conveyor system are mostly due to the temperature at which the coal is carried and also due to the attrition in the belt. By means of a Temperature sensor and an IR sensor this could be regularly monitored and during any abnormal situation, this initiate Cooling fan in case of high temperature and signals an alarm whenever there is any fault in the system.

Introduction

The Conveyor system is considered to be the least important system in Thermal Power station and hence Humans are employed to look after it on a shift basis. The Conveyor system in a Thermal Power station consists of various components like Conveyor gallery, Belt sway switch, Pull cord switch, Self-aligning roller, Zero speed switch, Counter weight. But apart from this, Conveyor belt has a significant role to carry the Coal without affecting its combustion quality to the Coal Crushing unit for further process. Normally, the Conveyor belt length varies from 300m to 1000m on an average basis. So, it becomes a tedious process to make sure that they are in perfect condition throughout the operating days without any damage in the belt. Since, mainly humans are employed in the Handling plants, they tend to make errors and any small such errors may cause a huge loss to life and property.

Existing system

At present, in most Thermal Power plants, there is no specific automated system used to monitor the status of the Coal conveyor system although, the rest of the Power plant is controlled and protected by means of advanced system like PLC and SCADA. The existing method in the Conveyor system makes use of manual skilled labor to regularly monitor the Conveyor belt. In case, of any fault identification the entire Conveyor system is turned off on a temporary basis until the fault is rectified completely. This affects the overall efficiency of the plant by minimizing the operation period which ultimately results to low output power. Hence, it is high time to switch over to automated system from manual monitoring techniques.

Proposed system

In the Proposed system, several features are employed to minimize the work load

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on humans. The system consists of LM 35 Temperature sensor and a Tear detecting IR sensor to detect any flaws in the Conveyor belt. The temperature sensor senses the temperature of the surroundings regularly, and whenever there is any rise in temperature, the signal passes to the PIC microcontroller which in turn switches on the Cooling fan thereby to reduce the excess temperature. Also, whenever there is any attrition in the Conveyor belt due to its quality or life-span, the Infra- Red sensor detects the flaw in the belt. This in turn makes the Microcontroller to stop the Conveyor system and initiate the alternative another conveyor system so that the Output power of the plant is not affected. (Figure 1).

Hardware components

A. Power supply: The Power supply available mostly is 230V AC. But this power is converted to +5V DC since, the optimal input power for the PIC Microcontroller is +5V DC. This is made possible by means of a Converter circuit consisting of various power electronic devices.

B. PIC microcontroller: The PIC microcontroller is chosen since it has a less power consumption compared to other microcontrollers. Main characteristic of this Microcontroller is that it can connect analog devices directly without any external circuitry and uses them with ease. Programming is also very easy when compared to other microcontrollers. It has the functions of reading the data available at the sensor output, send the data to the LCD display and operate the other motor in case of any faults in the belt. (Figure 2).

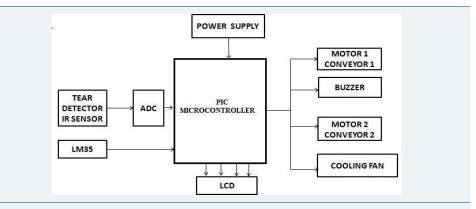


Figure 1: Block diagram of the Proposed system.

MCLR/VPP → 1	\bigcirc	40 □ RB7/PGD
RA0/AN0 - 2		39 □ RB6/PGC
RA1/AN1 → 3	3 4 5 6 7 8 8 4 7 8 4 7 8 4 7 8 4 7 8 4 7 8 4 7 8 7 8	38 🗖 🛶 🕨 RB5
RA2/AN2/VREF-/CVREF		37 □ - RB4
RA3/AN3/VREF+ - 5		36 □ - RB3/PGM
RA4/T0CKI/C1OUT		35 🗖 🛶 🗕 RB2
RA5/AN4/SS/C2OUT		34 🗖 🛶 RB1
RE0/RD/AN5 - 8		33 RB0/INT
RE1/WR/AN6 - 9		32 - VDD
RE2/CS/AN7 → 10		31 🗖 🖛 Vss
VDD► 11	87	30 -→ RD7/PSP7
Vss 12	6F	29 - ► RD6/PSP6
OSC1/CLKI 13	1	28 - RD5/PSP5
OSC2/CLKO - 14	PIC1	27 - RD4/PSP4
RC0/T10S0/T1CKI 15	L .,	26 - RC7/RX/DT
RC1/T1OSI/CCP2		25 - RC6/TX/CK
RC2/CCP1		24 - RC5/SDO
RC3/SCK/SCL 18		23 RC4/SDI/SD/
RD0/PSP0		22 - RD3/PSP3
RD1/PSP1 → □ 20		21 -→ RD2/PSP2

Figure 2: Pin diagram of PIC 16F877A.



C. Temperature sensor: The temperature sensor used in this proposed system is LM 35. It is a 3- pin analog temperature sensor which has high precision than mostly available sensors. The Pin-1 senses the temperature in the surroundings and gives output as a Voltage through Pin-2. The main advantage of using this sensor is that it can be operated at any harsh and extremely hot climatic conditions.

D. IR sensor: The two important components of an IR sensor are the IR LED and the Photo-diode. They are mostly used to detect any object motion and any deviation in a smooth surface. In this project, the IR sensor is employed to detect any flaws that occur in the smooth surface of the Coal conveyor belt.

E. DC motor: A DC motor is a class of rotary electrical machines that converts direct current energy into mechanical energy. The most common types rely on the forces produced by magnetic fields. The Operating range of the motor used in this project is 4V to 12V. The Speed is 30rpm at 12Vand Torque range is 5kg/c. The motors are designed to reduce the output speed while increasing its torque. The increasing torque is inversely proportional to reduction in speed.

F. Buzzer: The project makes use of electric buzzer to alert the persons in the remote stations in the thermal power plant. The Operating voltage of the buzzer is 1.5V to 12V. It produces sound range from 2 to 4 KHz. It is used to produce an alarming signal whenever there is fault in the system.

G. Cooling fan: The Cooling fan used in this project is a Brushless DC motor. The cooling fan starts to operate whenever there is abnormal or a high temperature is prevailing in the Coal conveyor belt resulting damage to it. The operating voltage of the Brushless DC motor is 8V to 12V. It operates when the LM 35 senses high temperature and initiates the PIC microcontroller to act accordingly.

Circuit description

A. **Temperature sensing circuit:** The Temperature sensing circuit mainly consists of LM 35 to regularly monitor the temperature of the coal in the Thermal Power station. Whenever the temperature reaches a high value or above the nominal range, a Fan is automatically turned in to remove the excess heat from the coal and to prevent any damage to the system. The temperature sensing circuit involves the use of the LM35 temperature sensor. The third pin connected to the ground and first pin connected to the 5V supply. The output from the second pin is connected to the channel AN1 of the microcontroller. A potentiometer is also connected between the second pin and the ground to calibrate the temperature sensor during the occurrence of faults. (Figure 3).

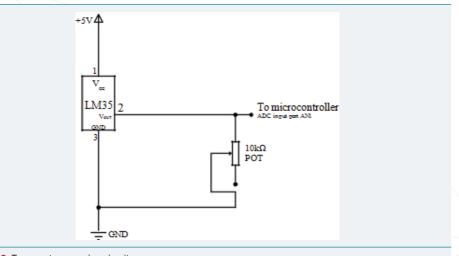
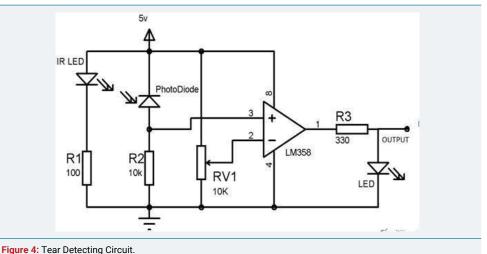


Figure 3: Temperature sensing circuit.



B. *Tear detecting circuit:* The Tear detecting circuit relies on the operation of an Infra-Red LED and a Photodiode. The combination of IR-LED and Photodiode detects any fault or abnormal deviation from the smooth surface. Whenever there is such deviation it integrates the voltage and compares it with the pre-set value. Mainly, these Tear detecting circuit is employed in areas profound to object motion (Figure 4).

C. **Overall circuit diagram:** The temperature sensor LM35 is placed above the Conveyor belt to regularly monitor the temperature of the coal. The tear detecting IR sensor is placed below the Conveyor system to detect any flaws like tear and cracks in the system. The output of these sensors is provided to the PIC microcontroller. PIC microcontroller is programmed to compare temperature in the system also to initiate the rotation of another conveyor belt in case of any faults in the belts. The temperature of the coal carried in the Conveyor belt and the working status of the entire system is shown in the LCD display regularly (Figure 5).





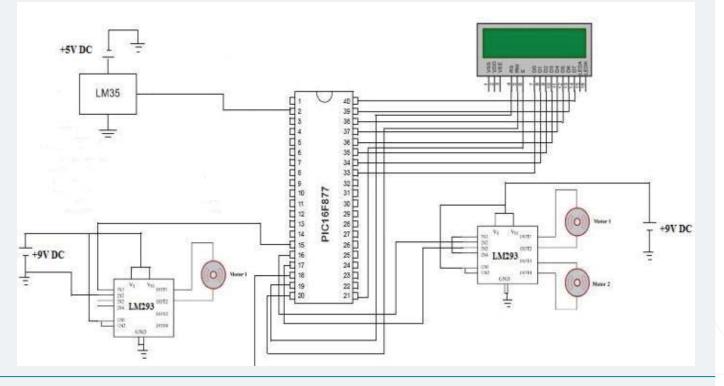


Figure 5: Overall Circuit diagram.



Conclusion

This Proposed system which makes use of Automatic system to regularly monitor the status of the Conveyor system is highly efficient since the operation of the Conveyor system is not at all interrupted during the occurrence of any fault in the belt. The addition of PIC microcontroller makes the overall system simple in design and operation. This system is found to be an efficient replacement for the existing manual monitoring system.

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